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Design of Hybrid Energy storage systems – Optimal sizing and control

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Problem statement

▲ Hybrid Energy Storage System (HESS)

- ▲ Satisfies both high specific energy and high specific power requirements
- ▲ Thus reduce over-sizing of energy storage systems such as batteries.

▲ Optimal system design of the Hybrid Battery system

- ▲ Lowest possible system size of both HP** & HE** Batteries
- ▲ Optimal powersplit control between HP & HE batteries

▲ To compare different battery topologies

- ▲ Cost of topology with lowest system cost

Solution

- ▲ Combine optimal sizing of different components of the battery with powersplit control
- ▲ Perform Codesign optimization

Hybrid Energy Storage Systems (HESS) - Topologies

Classes of hybrid electrical energy storage topologies (HESTs)

Passive HEST (P-HEST)

Discrete HEST (D-HEST)

Active HEST (A-HEST)

Parallel D-HEST (pD-HEST)

Serial D-HEST (sD-HEST)

Serial-parallel D-HEST (spD-HEST)

Parallel-serial D-HEST (psD-HEST)

Semi-active HEST (SA-HEST)

Parallel SA-HEST (pSA-HEST)

Battery SA-HEST (BSA-HEST)

Capacitor SA-HEST (CSA-HEST)

Full-active HEST (FA-HEST)

Cascaded FA-HEST (cFA-HEST)

Battery cFA-HEST (BcFA-HEST)

Capacitor cFA-HEST (CcFA-HEST)

Parallel FA-HEST (pFA-HEST)

Modular multilevel FA-HEST (MMFA-HEST)

Legend

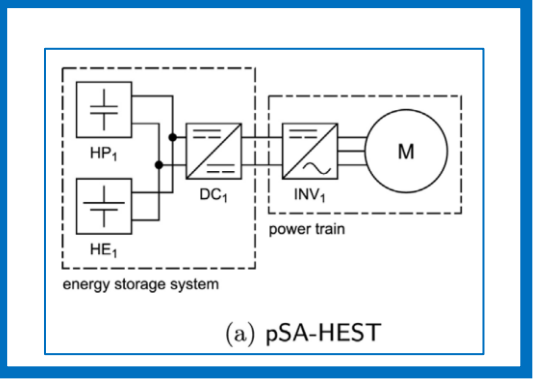
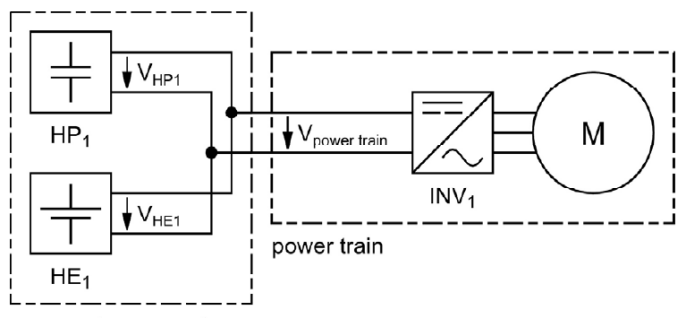
c: cascaded

p: parallel

s: serial

FA: Full-active

SA: Semi-active



-> 1 DC/DC converter
-> ESS connected in parallel

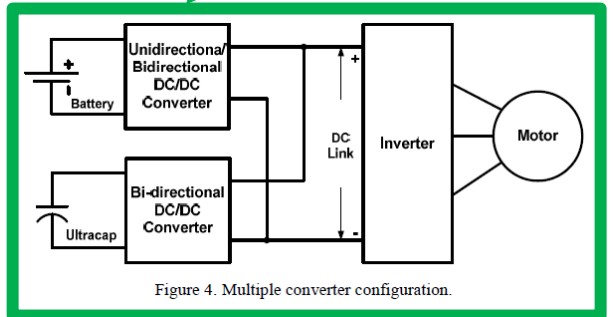


Figure 4. Multiple converter configuration.

-> 2 DC/DC converter
-> Full control over power distribution
-> Flexible ESS operating voltage range

-> No power electronics
-> No control over power distribution
-> Limited ESS operating voltage range

Discrete battery system

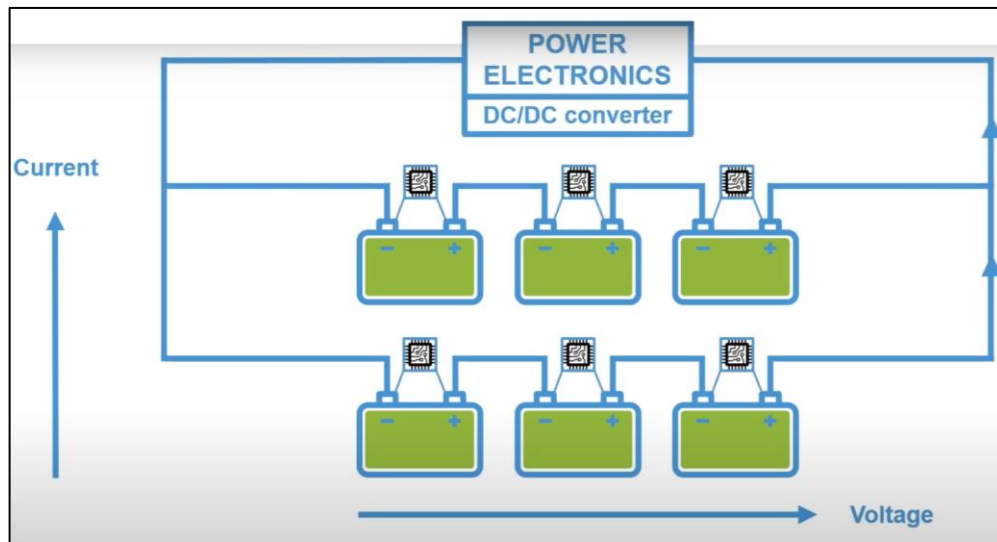
▲ **Conventional fixed battery systems**, → fixed interconnection between the cells

▲ Requires a DC/DC converter to regulate the output voltage for the load.

▲ **Discrete battery system** → battery interconnection pattern is changeable using switching elements. The switching elements allow to engage or bypass the cells

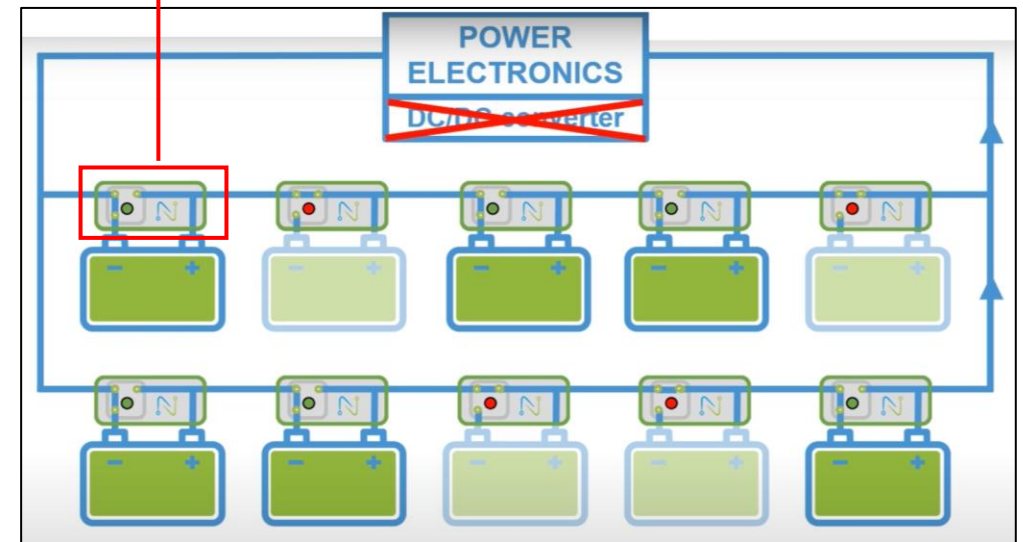
▲ No need of DC/DC converter to adapt dynamically to the load.

Fixed battery system



switching element ←

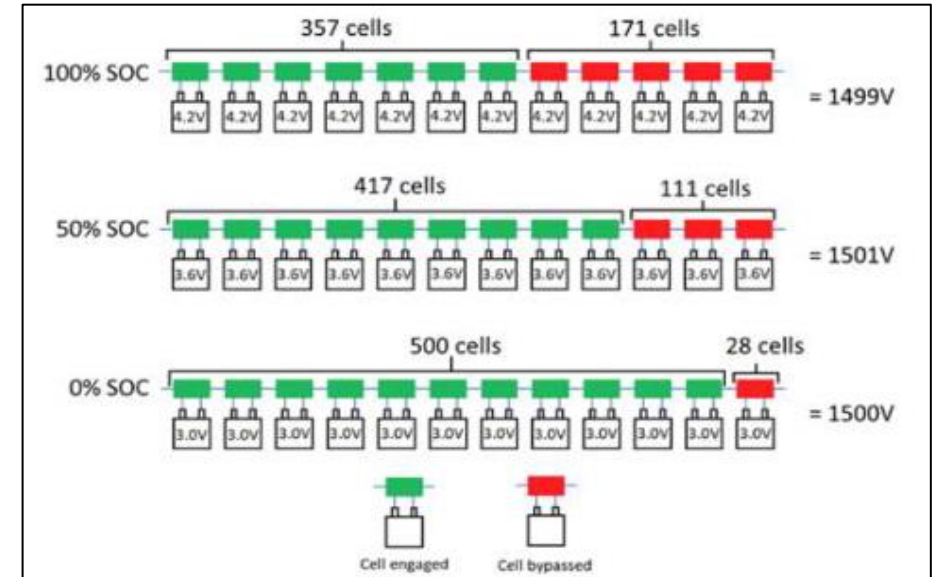
Discrete battery system



Discrete battery system

- No need of DC/DC converter
 - Customized terminal voltage by engaging/bypassing the cells
- Extended energy delivery
 - Schedule the operation of batteries for faster and enhanced energy conversion (e.g., putting cells to rest once they have reached the upper voltage limit)
- Charge and Temperature Balancing
 - Cell balancing is possible without any additional balancing circuitry
- Enhanced fault tolerance and safety
 - Quickly disconnect faulty cells while reconnecting the remaining normal ones

Engaging the cells to achieve a constant voltage



Fixed battery system



STANDARD BATTERY |

Discrete battery system



RELECTRIFY BATTERY |

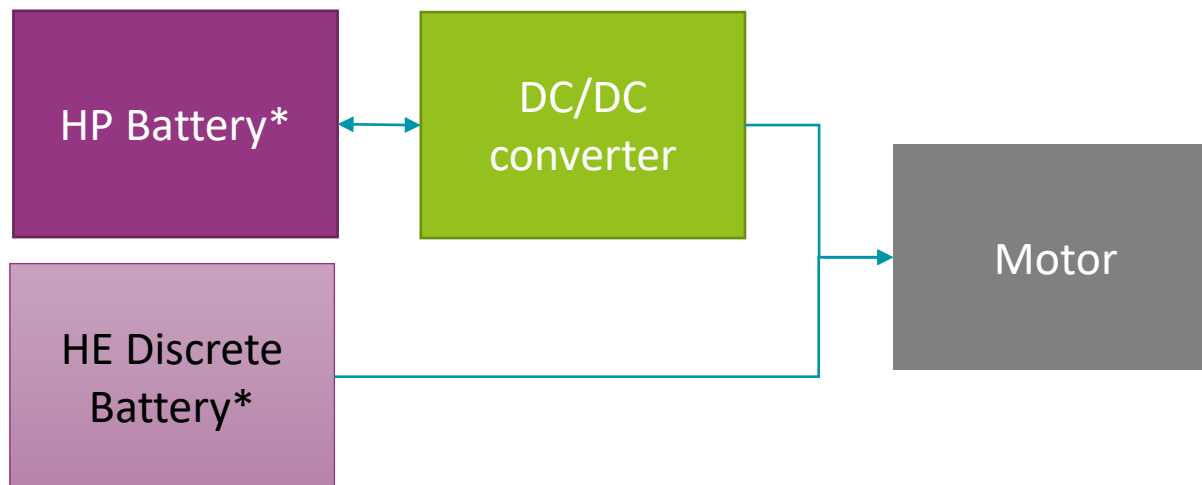
Selected Battery topologies

1) Baseline Monotype Battery system



- Typical battery system found in most electric marine applications
- DC/DC converter ensures constant input voltage to the motors

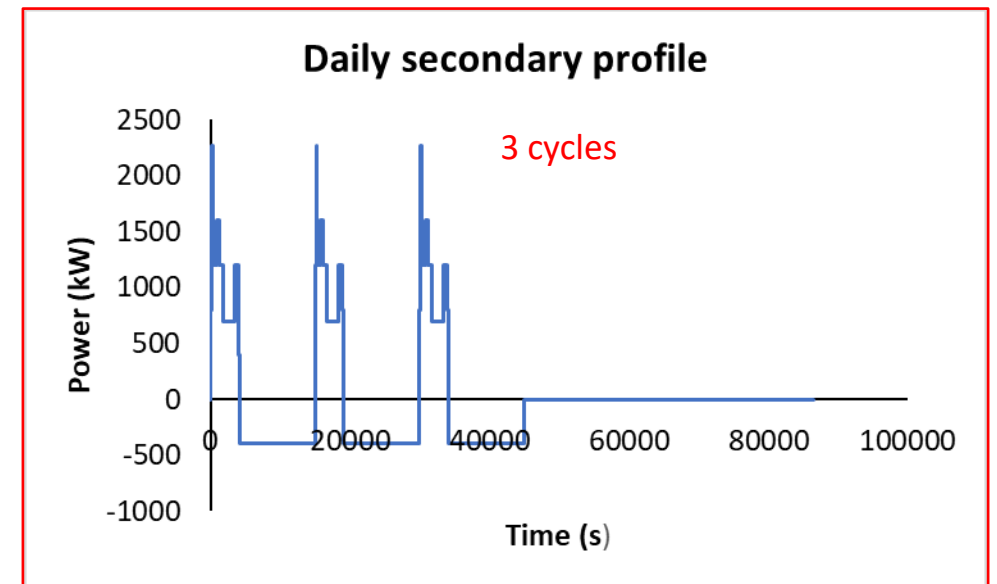
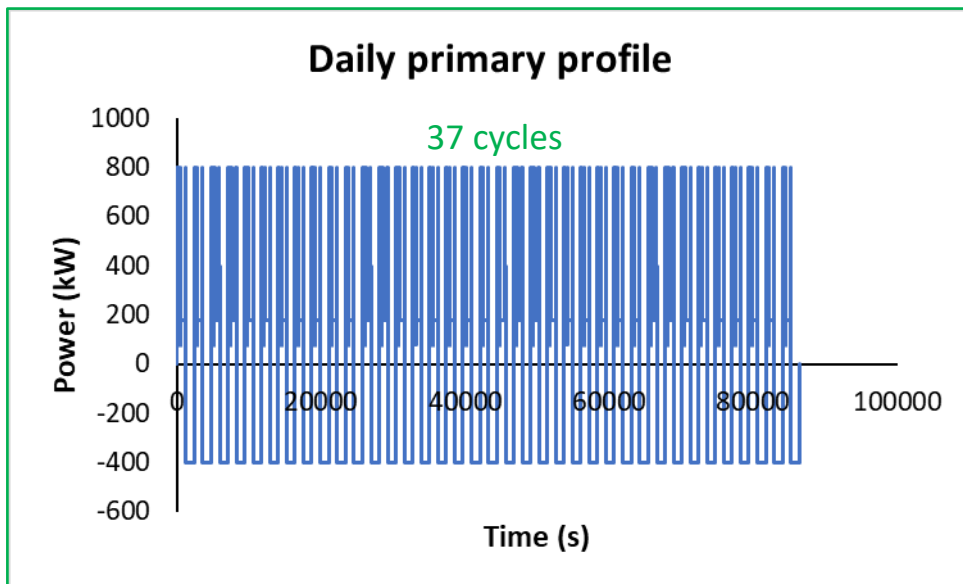
2) Discrete hybrid battery system



- Discrete hybrid battery system proposed as a cost efficient and better alternative to Baseline monotype battery pack.
- HE Battery is discrete battery. Switches present in each cell maintain the required input voltage to the Motor
- HP Battery is typical battery

Application load cycle- Ro-Ro ferry 1

- Ro-Ro ferry 1 has a season dependent operational profile.
- Primary profile: A summer profile, 335 days per year making 37 cycles per day which requires 124 kWh energy
- Secondary profile: During winter, 30 days per year, making 3 cycles per day which requires 1200 kWh energy
- **Annual primary cycles ($N_{P-cycles}$):** 123950 cycles per 10 years
- **Annual secondary cycles ($N_{S-cycles}$):** 900 cycles per 10 years



Battery model – SoC and SoH

Battery State Of Charge (SoC) model

- Same for Baseline (NMC), HP (LTO) & HE (NMC) battery

$$SoC(t_{k+1}) = SoC(t_k) + \Delta SoC$$
$$\Delta SoC = \frac{P_{batt}}{Cap_{batt}} * 100$$

- We assume 100% efficiency of battery to simplify the system.
- Constraint :- Limit 10% < SoC < 90%

Battery lifetime model – State Of Health (SoH)

- Same for Baseline (NMC), HP (LTO) & HE (NMC) battery
- SoH degraded after 10 years

$$SoH_{10\text{ years}} = 100 - Cycle\ ageing_{10\text{ years}} - Calendar\ ageing_{10\text{ years}}$$
$$Cycle\ ageing_{10\text{ years}} = \frac{1}{Cycle\ life} \left\{ N_{P-cycles} \int |\Delta SoC|_{Primary\ cycle} + N_{S-cycles} \int |\Delta SoC|_{Secondary\ cycle} \right\}$$
$$Calendar\ ageing_{10\text{ years}} = \frac{Standby\ time_{batt}}{365} * 10 = 1\% \text{ SoH per year of standby}$$

- Constraint :- End of life capacity = $SoH_{10\text{ years}} \geq 80\%$

Minimization function :- Topology cost

Topology cost for Baseline topology

$$\text{Topology Cost}_{\text{Baseline}} = \text{Cost}_{\text{cells}} + \text{Cost}_{\text{DC/DC}}$$

$$\text{Cost}_{\text{cells}} = N_{\text{cells}} * \text{Cost per cell}$$

$$N_{\text{cells}} = \text{Ceil} \left[\frac{\text{Cap}_{\text{batt}}}{\text{Cap}_{\text{cell}}} \right]$$

$$\text{Cost}_{\text{DC/DC}} = \text{Cost per KW}_{\text{DC/DC}} * \max(P_{\text{load cycle}})$$

Topology cost for Discrete Hybrid topology

$$\text{Topology Cost}_{\text{Discrete-Hybrid}} = \text{Cost}_{\text{HP cells}} + \text{Cost}_{\text{HP DC/DC}} + \text{Cost}_{\text{HE cells}} + \text{Cost}_{\text{HE switches}}$$

$$\text{Cost}_{\text{HP/HE cells}} = N_{\text{HP/HE cells}} * \text{Cost per cell}$$

$$N_{\text{HP/HE cells}} = \text{Ceil} \left[\frac{\text{Cap}_{\text{HP/HE batt}}}{\text{Cap}_{\text{HP/HE cell}}} \right]$$

$$\text{Cost}_{\text{HP DC/DC}} = \text{Cost per KW}_{\text{HP DC/DC}} * \max(P_{\text{HP batt}})$$

$$\text{Cost}_{\text{HE switches}} = \text{Cost of 2 switches per cell} + \text{Control circuit}$$

Optimization approach – Codesign Optimization

Step 1 :- Define Optimization Parameters :- (Unknown)

- a) Baseline battery topology – Capacity of battery
- b) Discrete Hybrid battery topology - Capacity of HP battery, Capacity of HE battery, Powersplit at each sample time

Step 2 :- Model the system i.e Batteries and DC/DC converter as a function of optimization parameters
Baseline – NMC; HP battery – LTO; HE battery - NMC

Step 3 :- Optimization formulation :-

Constraints :-

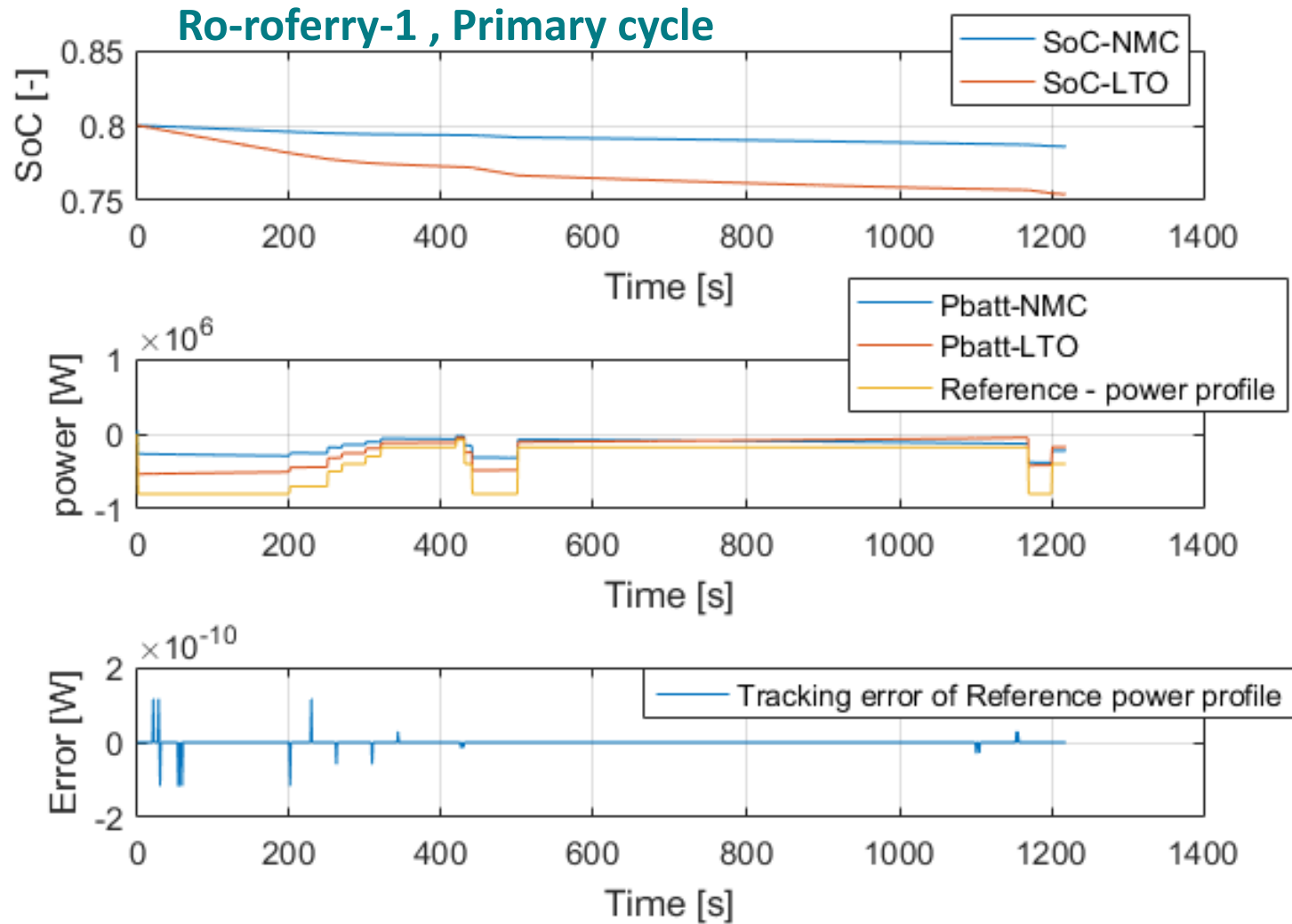
1. SoC range – [10% , 90%]
2. End of life capacity \geq 80%
3. Max. charging/ discharging power of each Battery
4. Satisfy the Required Power by the Load cycle

Step 4 :- Objective function :- Minimize Topology cost

▲ Optimization constraints and Objective function is modelled as a function of optimization parameters.

▲ Optimization problem is solved using Direct Multiple shooting optimization technique.

Optimization results :- Only Power-split optimization



Power-split optimization for Specific size

Capacity of NMC = 3481 kWh

Capacity of LTO = 1495 kWh

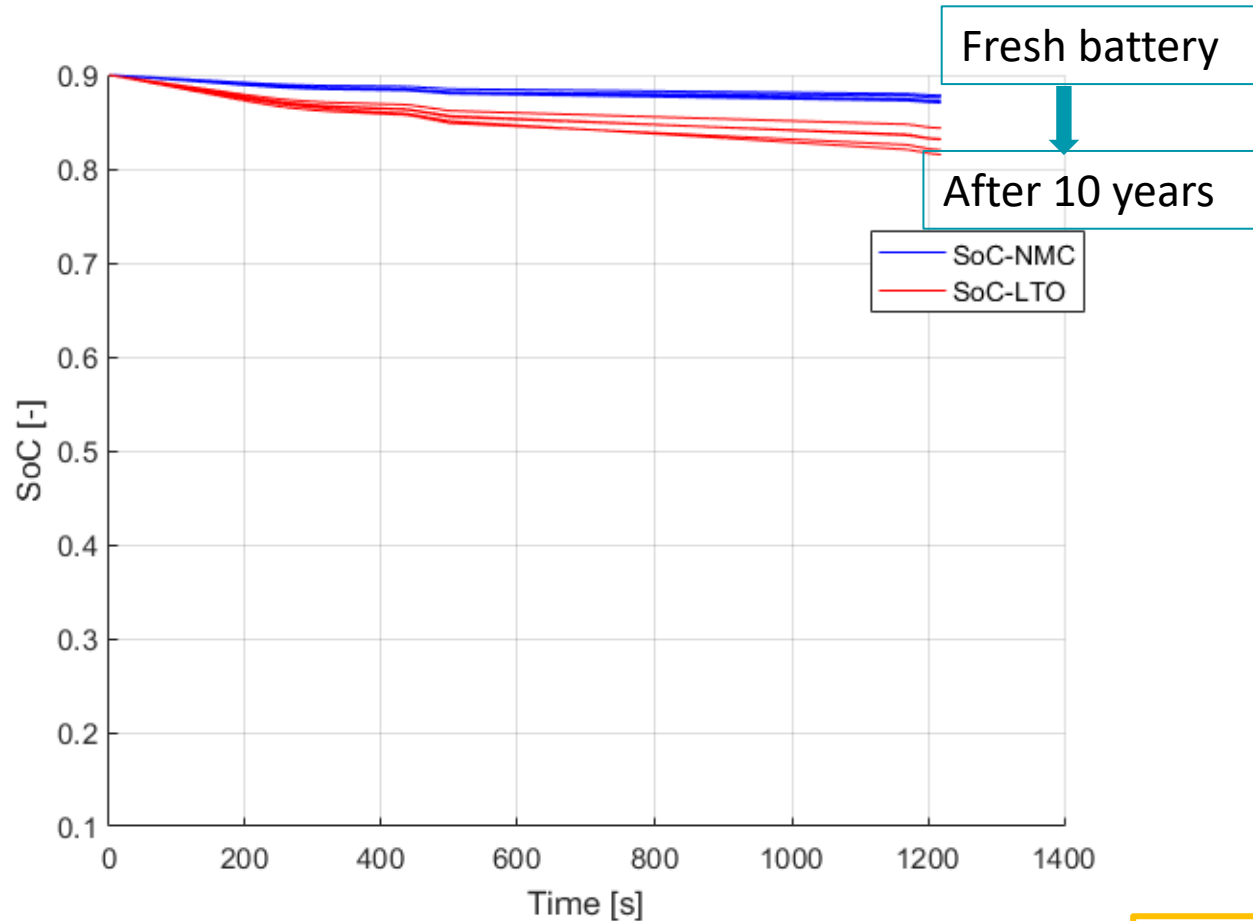
SoH degradation < 20% -NMC, LTO

SoH degradation = 1 cycle degradation * No. of primary cycles in 10 years

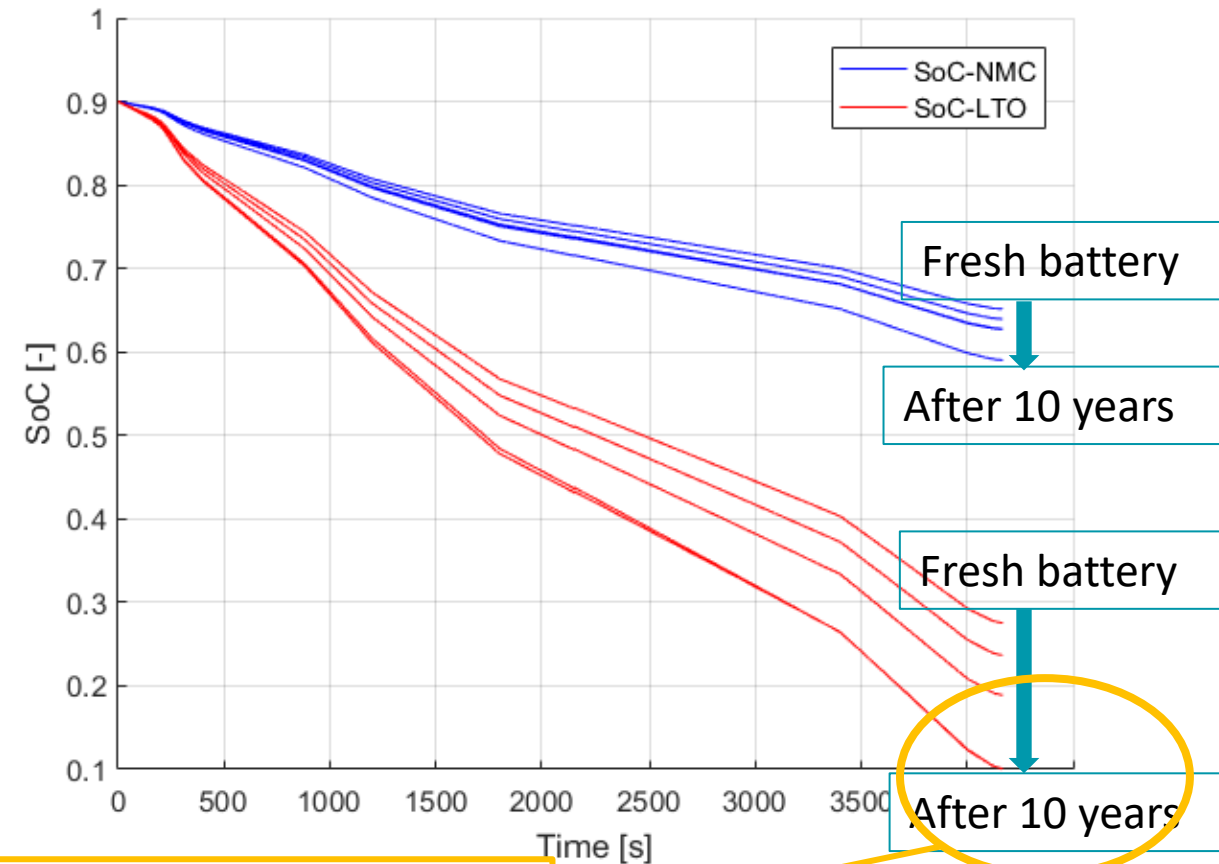
Optimization results :- Both Power split and Sizing optimization

RoRoferry-1 – Optimal powersplit at different years of use

Primary load profile – Summer



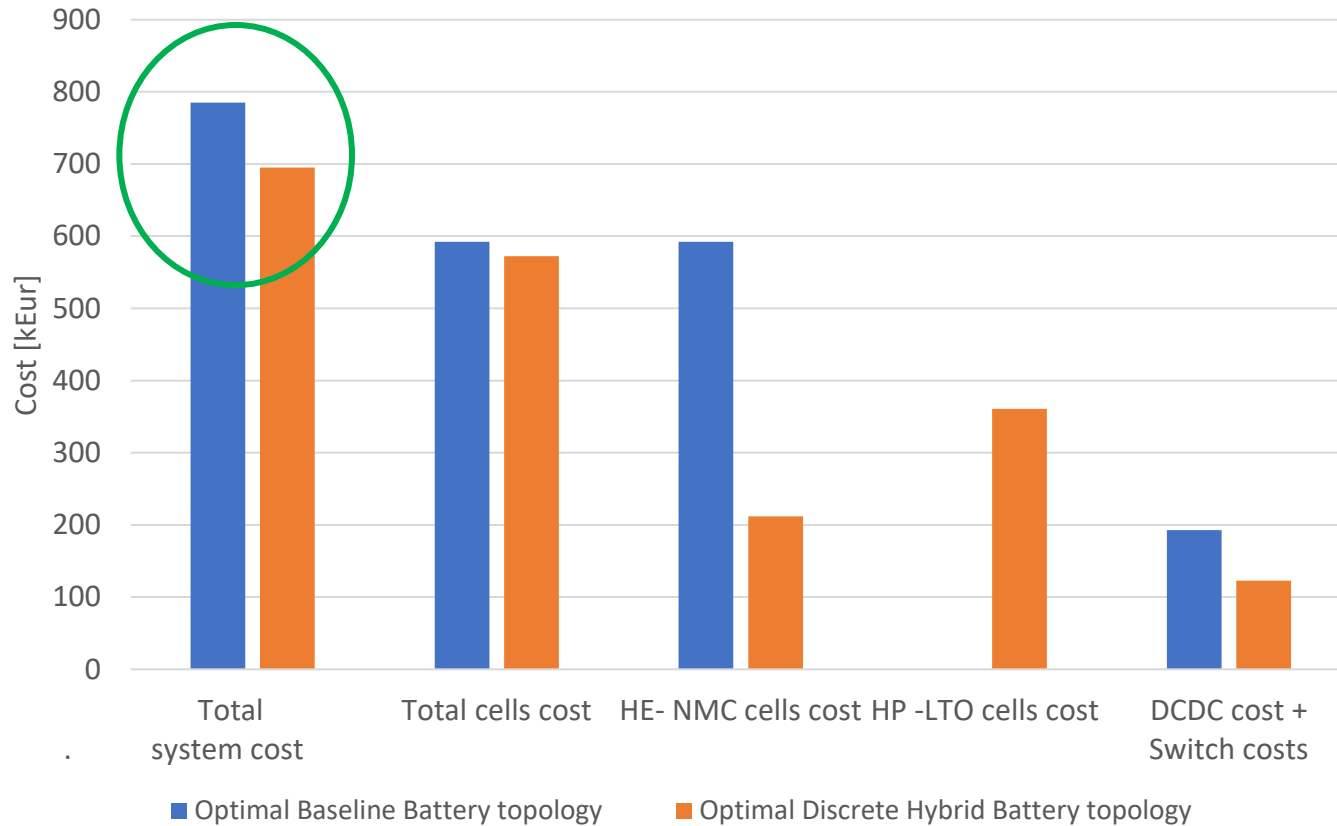
Secondary load profile - Winter



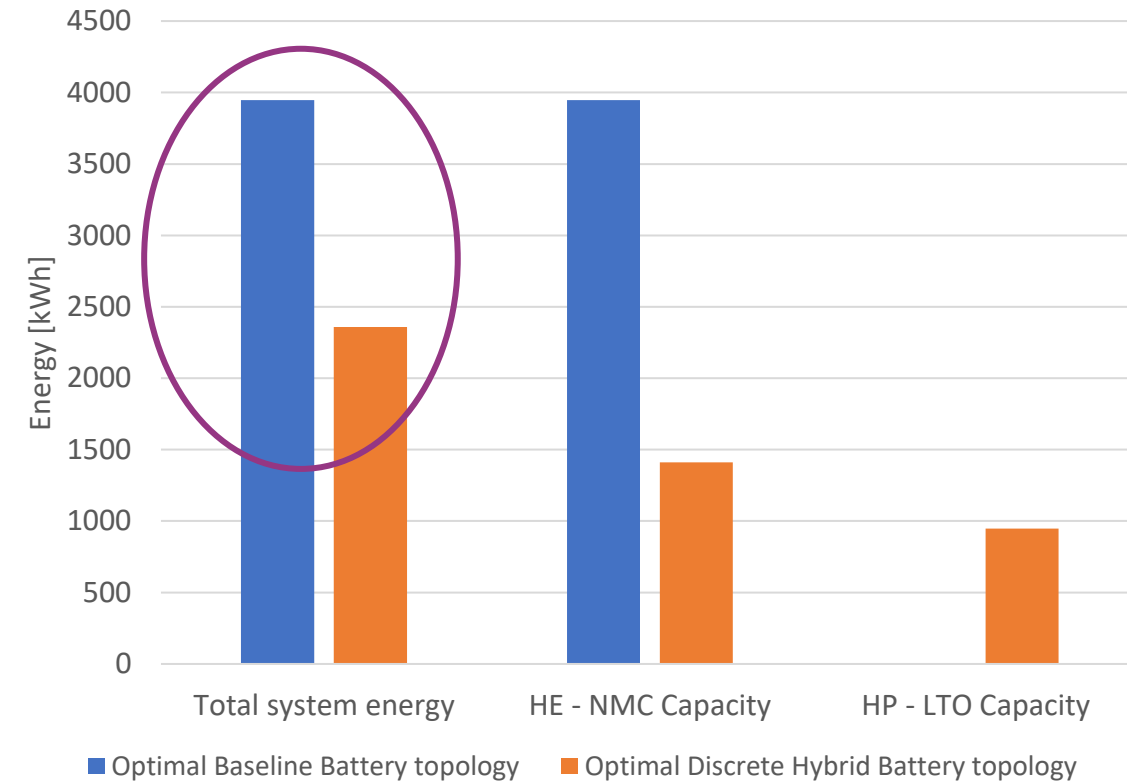
LTO battery Reaches the minimum SoC at the End of Life

Results of the optimization – RoRoferry-1

Cost comparison of topologies



Energy capacities of topologies



- 12.8 % Total system Cost reduction for Discrete Hybrid topology
- 67 % Total energy reduction for Discrete Hybrid topology

Conclusion

- △ Different battery topologies (Hybrid) can be compared to find the cost-effective topology for a specific application
- △ Optimal design for Hybrid Energy storage system is performed
- △ Provides the optimal total cost of the system ensuring all the constraints
- △ Ensures the powersplit control is optimal for the system specification
- △ Discrete hybrid battery topology is cost-effective compared to Baseline topology for RoRoferry-1



Thank you

